

11. MERTON PORTFOLIO OPTIMIZATION

SINGLE ASSET CASE:

STOCK OBEYS: $dS_t = S_t \{ \sigma dB_t + \mu dt \}$, $n_t = \# \text{ OF STOCKS}$

BANK OBEYS: $dm_t = m_t r dt$ $m_t = \text{MONEY IN BANK}$

WEALTH OBEYS:

$$dW_t = \underbrace{r \underbrace{m_t}_{(W_t - n_t S_t)}}_{\text{MONEY IN BANK}} dt + \underbrace{n_t}_{\text{MONEY IN STOCKS}} dS_t - \underbrace{c_t}_{\text{CONSUMPTION}} dt$$

THE MERTON PROBLEM:

$$V(w_0) = \max_{(n_t, c_t)_{t \geq 0} \in \mathcal{P}(w_0)} \mathbb{E} \left[\int_0^\infty e^{-\rho t} u(c_t) dt \right].$$

CONCAVE INCREASING
DIFFERENTIABLE FN.

THE BELLMAN EQUATION:

Prop 74. The HJB equation for the Merton Problem can be written as

$$0 = \max_c \{u(c) - c\partial_w V\} + \max_\theta \left\{ \theta(\mu - r)\partial_w V + \frac{1}{2}\sigma^2\theta^2\partial_{ww} V \right\} - \rho V + rw\partial_w V$$

Here the optimal θ and c are given by

$$\theta^* = -\frac{\partial_w V}{\partial_{ww} V}\sigma^{-2}(\mu - r), \quad c^* = (u')^{-1}(\partial_w V)$$

PROOF:

$$\begin{aligned} dW_t &= r(W_t - n_t S_t)dt + \underbrace{n_t dS_t}_{n_t S_t dt + n_t S_t \sigma dB_t} - c_t dt \\ &= (rW_t + (\mu - r)\theta_t - c_t)dt + \theta_t \sigma dB_t \end{aligned}$$

$$\left[0 = \max_a \left\{ \text{"INSTANTANEOUS COST"} - \rho V + \text{"DRIFT FROM ITO'S FORMULA"} \right\} \right]$$

Proof:

$$dV(W_t) = \partial_w V(W_t) dW_t + \frac{1}{2} \partial_{ww} V(W_t) d[W_t]$$

$$= \partial_w V(W_t) [r(W_t - n_t S_t) dt + n_t dS_t - c_t dt] + \frac{\theta^2 \sigma^2}{2} \partial_{ww} V(W_t) dt$$

$\therefore$ HJB IS

$$0 = \max_{\theta, c} \left\{ u(c) - \rho V + (rW + \theta(\mu - r) - c) \partial_w V + \frac{1}{2} \sigma^2 \theta^2 \partial_{ww} V \right\}$$

$$= \underbrace{\max_c \{ u(c) - c \partial_w V \}}_{\Rightarrow u'(c) = \partial_w V} + \underbrace{\max_{\theta} \left\{ \theta(\mu - r) + \frac{1}{2} \sigma^2 \theta^2 \partial_{ww} V \right\}}_{\Rightarrow -(\mu - r) \partial_w V = \sigma^2 \theta \partial_{ww} V} - \rho V + rW \partial_w V$$

$$\Rightarrow u'(c) = \partial_w V$$

$$\Rightarrow -(\mu - r) \partial_w V = \sigma^2 \theta \partial_{ww} V$$

□

GIVES THE
CONDITION ON
 θ, c ABOVE

PROP IS GOOD BUT WE NEED TO FIND $\partial_w V$, $\partial_{ww} V$.

MERTON FOR CRRA UTILITY

FOR $R > 0$

$$u(c) = \frac{c^{1-R}}{1-R}$$

$$(\text{ } = \log c \quad \text{IF } R=1)$$

CONSTANT RELATIVE
← RISK AVERSION (CRRA)

[[?] MEANS SAME ATTITUDE TO RISK IN A BET
IF YOU MULTIPLY THE STAKES]

SO WE SOLVE FOR

$$V(w_0) = \max_{(n_t, c_t)_{t \geq 0}} \mathbb{E} \left[\int_0^\infty e^{-\rho t} \frac{c_t^{1-R}}{1-R} dt \right].$$

Prop 75. For a CRRA utility it holds that:

a) The Value function takes the form

$$V(w) = \gamma \frac{w^{1-R}}{1-R}$$

so we can
DIFFERENTIATE
 $V(\cdot)$

for some position constant $\gamma > 0$.

b) The HJB equation is optimized by

$$\theta^* = \frac{w}{R} \sigma^{-2} (\mu - r),$$

& GET θ^*
& c^*
↓

$$c^* = \gamma^{-\frac{1}{R}} w \quad \text{and} \quad \sup_c \{u(c) - c \partial_w V\} = \frac{R}{1-R} \gamma^{1-\frac{1}{R}} w^{1-R}.$$

c) The HJB equation is satisfied by parameters

$$\gamma^* = R^{-1} \left\{ \rho + (R-1) \left(r + \frac{1}{2} \frac{\kappa^2}{R} \right) \right\}$$

where

$$\kappa = \sigma^{-1} (\mu - r).$$

Proof: a)
$$V(\lambda w) = \max_{(n_t, c_t)_{t \geq 0} \in \mathcal{P}(\lambda w_0)} \mathbb{E} \left[\int_0^\infty e^{-\rho t} \frac{c_t^{1-R}}{1-R} dt \right]$$

$$= \max_{(n_t, c_t)_{t \geq 0} \in \mathcal{P}(w_0)} \mathbb{E} \left[\int_0^\infty e^{-\rho t} \frac{(\lambda c_t)^{1-R}}{1-R} dt \right] = \lambda^{1-R} V(w).$$

Now let $\lambda = \frac{1}{w}$ & $\gamma = (1-R)V(1)$ gives $V(w) = \gamma \frac{w^{1-R}}{1-R}$

b) $\partial_w V = \gamma w^{-R}$, $\partial_{ww} V = -R \gamma w^{-R-1}$

$$\theta^* = - \frac{\partial_w V}{\partial_{ww} V} \sigma^{-2} (\mu - r) = \frac{w}{R} \frac{(\mu - r)}{\sigma^2}$$

[From previous Prop]

Also ↓

$$u'(c) = \partial_w V = \gamma w^{-R} \Rightarrow c = \gamma^{-\frac{1}{R}} w$$

" c^{-R}

PROOF (CONT)

$$\begin{aligned}\sup_c \{u(c) - c\partial_w V\} &= \frac{c^{*1-R}}{1-R} - c^* \partial_w V(c^*) \\ &= \frac{(\gamma^{-\frac{1}{R}} w)^{1-R}}{1-R} - (\gamma^{-\frac{1}{R}} w) \gamma w^{-R} \\ &= \frac{R}{1-R} \gamma^{1-\frac{1}{R}} w^{1-R},\end{aligned}$$

A BENE CALCULATED!

SUBSTITUTE INTO HJB EQU FOR γ :

$$\begin{aligned}0 &= \frac{R}{1-R} \gamma^{1-\frac{1}{R}} w^{1-R} - \frac{1}{2} \sigma^{-2} (\mu - r)^2 \frac{(\partial_w V)^2}{\partial_{ww} V} - \rho V + r w \partial_w V \\ &= \frac{R}{1-R} \gamma^{1-\frac{1}{R}} w^{1-R} - \frac{1}{2} \sigma^2 (\mu - r)^2 \frac{(\gamma w^{-r})^2}{(-R \gamma w^{-R-1})} - \rho \gamma \frac{w^{1-R}}{1-R} \\ &= \gamma w^{1-R} \left[\frac{R}{1-R} \gamma^{\frac{1}{R}} + \frac{1}{2} \sigma^2 \frac{(\mu - r)^2}{R} - \frac{\rho}{1-R} + r \right].\end{aligned}$$

A QUICK SUMMARY SO FAR:

To summarize: we notice we have shown that the parameters

$$\theta^* = \frac{w}{R} \sigma^{-2} (\mu - r), \quad c^* = \gamma^{-\frac{1}{R}} w, \quad (2.7a)$$

$$\gamma^* = R^{-1} \left\{ \rho + (R-1) \left(r + \frac{1}{2} \frac{\kappa^2}{R} \right) \right\}, \quad \kappa = \sigma^{-1} (\mu - r). \quad (2.7b)$$

&

$$W_t = W_0 \exp \left\{ R^{-1} \kappa \mathbf{B}_t + \left(r + \frac{1}{R^2} \kappa^2 (2R_1) - \gamma \right) t \right\}$$

&

Thrm 97. *The parameters in (2.7), above, are optimal for the Merton problem.*

↑
[SEE NOTES FOR
A PROOF]

MULTIPLE ASSETS:

[SAME AS BEFORE JUST A BIT MORE MESSY].

IF

$$dS_t^i = S_t^i \left\{ \sum_{j=1}^N \sigma^{ij} dB_t^j + \mu^i dt \right\}, \quad i = 1, \dots, d$$

FOR

$$dW_t = r(W_t - n_t \cdot S_t) dt + n_t \cdot dS_t - c_t dt$$

THEN HJB

$$0 = \max_{\theta, c} \left\{ \underbrace{u(t, c)}_{\text{CRA AGAIN.}} + \partial_t V + (rw + \theta \cdot (\mu - r) - c) \partial_w V + \frac{1}{2} |\sigma^\top \theta|^2 \partial_{ww} V \right\}.$$

& OPTIMAL

PARAMETERS ARE

$$\theta^* = \frac{w}{R} (\sigma \sigma^\top)^{-1} (\mu - r), \quad c^* = \gamma^{-\frac{1}{R}} w$$

$$\gamma^{-\frac{1}{R}} = R^{-1} \left\{ \rho + (R-1) \left(r + \frac{1}{2} \frac{|\kappa|^2}{R} \right) \right\} \quad \kappa = \sigma^{-1} (\mu - r).$$

GENERAL UTILITIES:

$$0 = \max_{\theta, c} \left\{ \underbrace{u(t, c)}_{\substack{\text{INCREASING} \\ \text{CONCAVE} \\ \lim_{c \rightarrow \infty} u'(t, c) = 0}} + \partial_t V + (rw + \theta \cdot (\mu - r) - c) \partial_w V + \frac{1}{2} |\sigma^\top \theta|^2 \partial_{ww} V \right\}.$$

LET $u^*(t, z) = \max_c \{u(t, c) - zc\}$ & $J(t, z) = V(t, w) - wz$ FOR $z = \partial_w V(t, w)$.

Thrm 99. The HJB equation can be written as

$$0 = u^*(t, c) + \partial_t J - rz \partial_z J + \frac{1}{2} |\kappa|^2 z^2 \partial_{zz} J$$

Moreover if we suppose that $u(t, x) = e^{-\rho t} u(x)$, for $u(x)$ concave and increasing, the HJB equation becomes

$$0 = u^*(y) - \rho j(y) + (\rho - r) y j'(y) + \frac{1}{2} |\kappa|^2 y^2 j''(y)$$

PROOF: FIRST WE SHOW $\partial_z J = -\omega$, $\partial_{zz} J = -\frac{1}{\partial_\omega V}$ $\partial_t J = \partial_t V$

$$J(z) = V(\underbrace{V'^{-1}(z)}_{=\omega}) - \underbrace{z V'(z)}_{=\omega}$$

$$\therefore J'(z) = \frac{d}{dz}(V'(z)) \cdot \underbrace{V'(V'^{-1}(z))}_z - \cancel{z \frac{d}{dz} V'(z)} - \underbrace{V'^{-1}(z)}_{=\omega} = -\omega$$

&

$$\therefore J''(z) = -\frac{d}{dz}(V')^{-1}(z) = -\frac{1}{V''(V'^{-1}(z))} = -\frac{1}{V''(\omega)}$$

&

$$\frac{\partial J}{\partial t} = \partial_t V(t, \omega) + \cancel{\frac{d\omega}{dt} \partial_\omega V} - \cancel{z \frac{d\omega}{dt}} = \partial_t V$$

HJB IS

$$0 = \max_c \{ u(t, z) - c \partial_\omega V \} + \max_\theta \left\{ \theta \cdot (\mu - r) \partial_\omega V + \frac{1}{2} |\sigma \theta|^2 \partial_{\omega\omega} V \right\} + \partial_t V + r \omega \partial_\omega V$$

$$= u^*(t, \underbrace{\partial_\omega V}_z) - \frac{1}{2} |k|^2 \underbrace{(\partial_{\omega\omega} V)^2}_{z^2} \underbrace{\frac{1}{\partial_{zz} J}}_{\partial_{zz} J} + \underbrace{\partial_t V}_{\partial_t J} + r \omega \underbrace{\partial_\omega V}_{-\partial_z J z}$$

$$= u^*(t, z) + \frac{1}{2} |k|^2 z^2 \partial_{zz} J + \partial_t J - r z \partial_z J.$$

PROOF (CONT)

[SIMILAR TO
CRRA ARGUMENT]

CAN CHECK IF $u(t, x) = e^{-\rho t} u(x)$ THEN $V(t, w) = e^{-\rho t} V(w)$

LETTING $j(z) = V(w) - wz$, $z = \partial_w V(t, w)$

THEN, DIFFERENTIATING GIVES

$$J(t, z) = e^{-\rho t} j(y),$$

$$\partial_t J = -\rho e^{-\rho t} j(y) + \rho e^{-\rho t} y j'(y)$$

$$\partial_z J = j'(y),$$

$$\partial_{zz} J = e^{\rho t} j''(y)$$

SUBSTITUTING INTO HJB EQUATION ABOVE GIVES:

$$0 = \underbrace{u^*(t, z)}_{=e^{-\rho t} u^*(y)} + \underbrace{\partial_t J}_{=-\rho e^{-\rho t} j(y) + \rho e^{-\rho t} y j'(y)} - \underbrace{rz \partial_z J}_{re^{-\rho t} y j'(y)} + \underbrace{\frac{1}{2} |\kappa|^2 z^2 \partial_{zz} J}_{\frac{1}{2} |\kappa|^2 y^2 e^{-\rho t} j''(y)}$$

□

$$V(w) = \max_{(\boldsymbol{n}_t, c_t)_{t \geq 0} \in \mathcal{P}(w_0)} \mathbb{E} \left[\int_0^\infty e^{-\rho t} u(c_t) dt \right].$$

$$j(z) \; = \; V(w) \; - \; wz$$